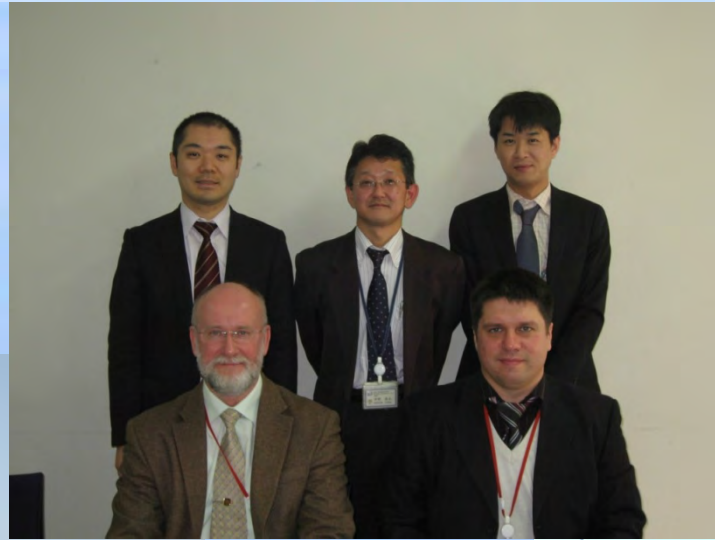


Procedures for correcting *in situ* CTD data and results obtained during the NEAR-GOOS Cross-Basin Climate Monitoring Section project



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²Far Eastern Federal University (FEFU), Vladivostok, Russia

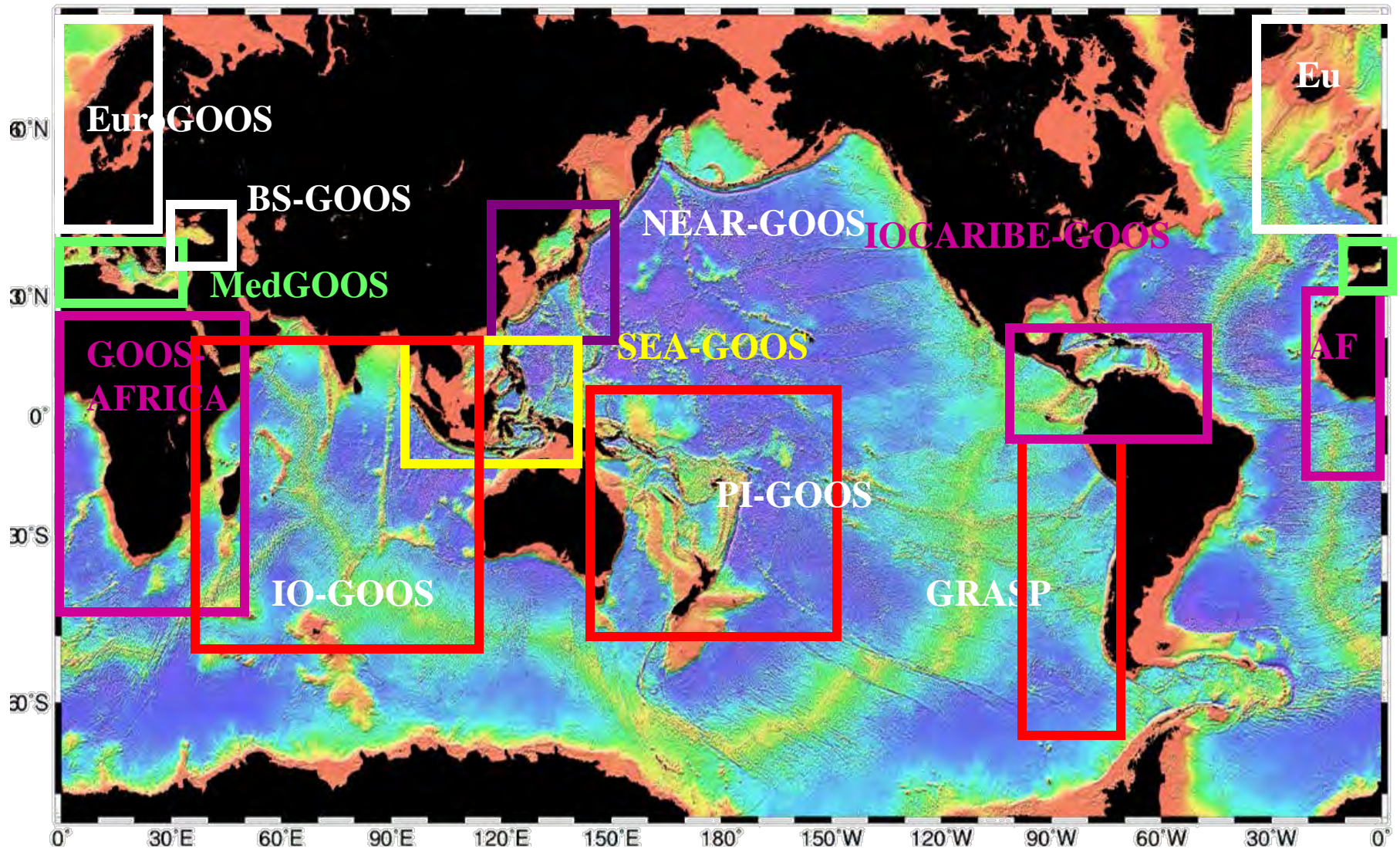
³Japan Meteorological Agency (JMA), Japan

e-mail: dimkap@poi.dvo.ru

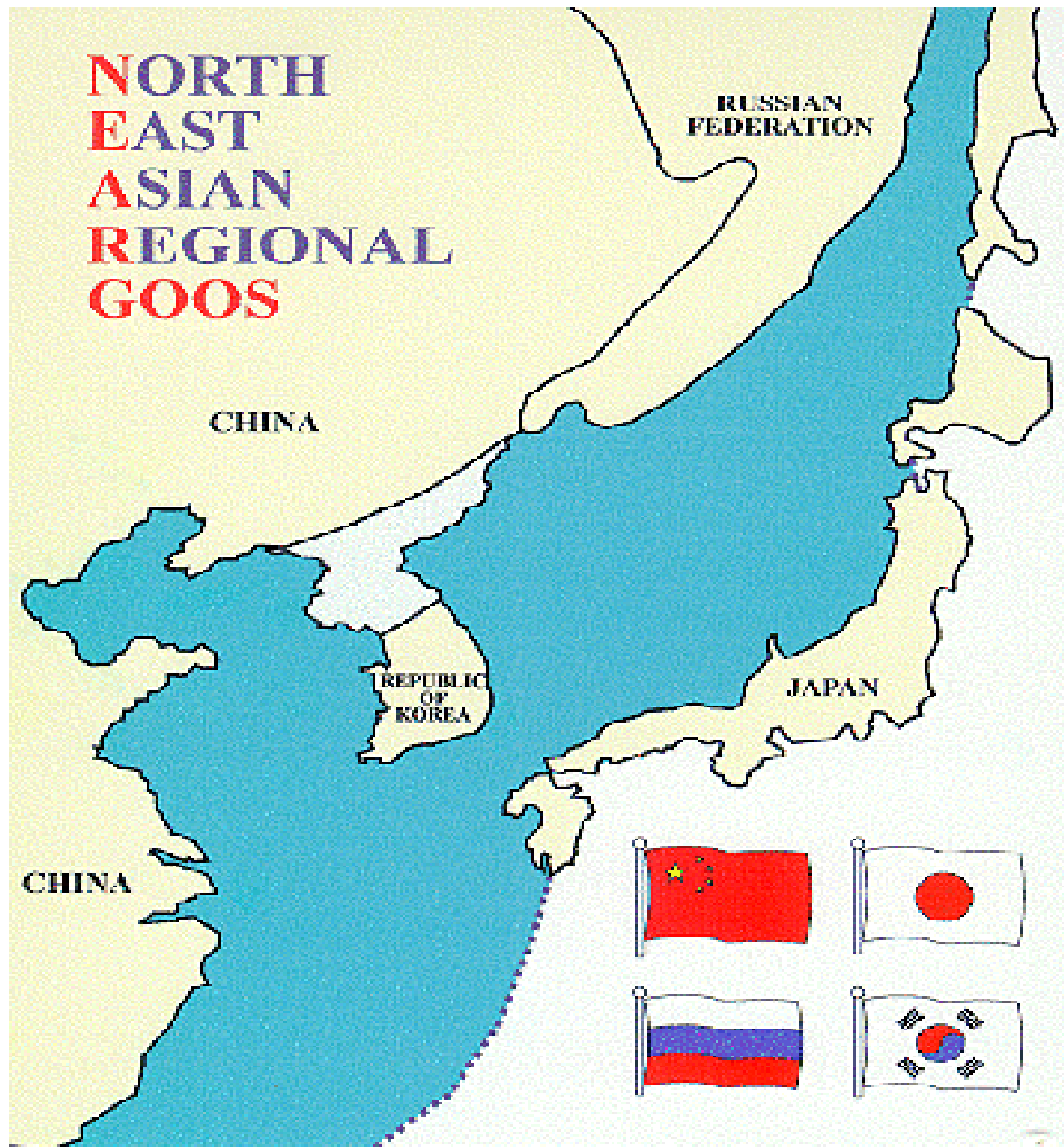
Contents

- NEAR-GOOS features
- Cross-Basin Climate Monitoring Section
- Precision of used sensors and data processing features
- JMA-POI data comparison
- Calibration results
- A hints on applying of calibrated data
- Conclusions

GOOS Regions

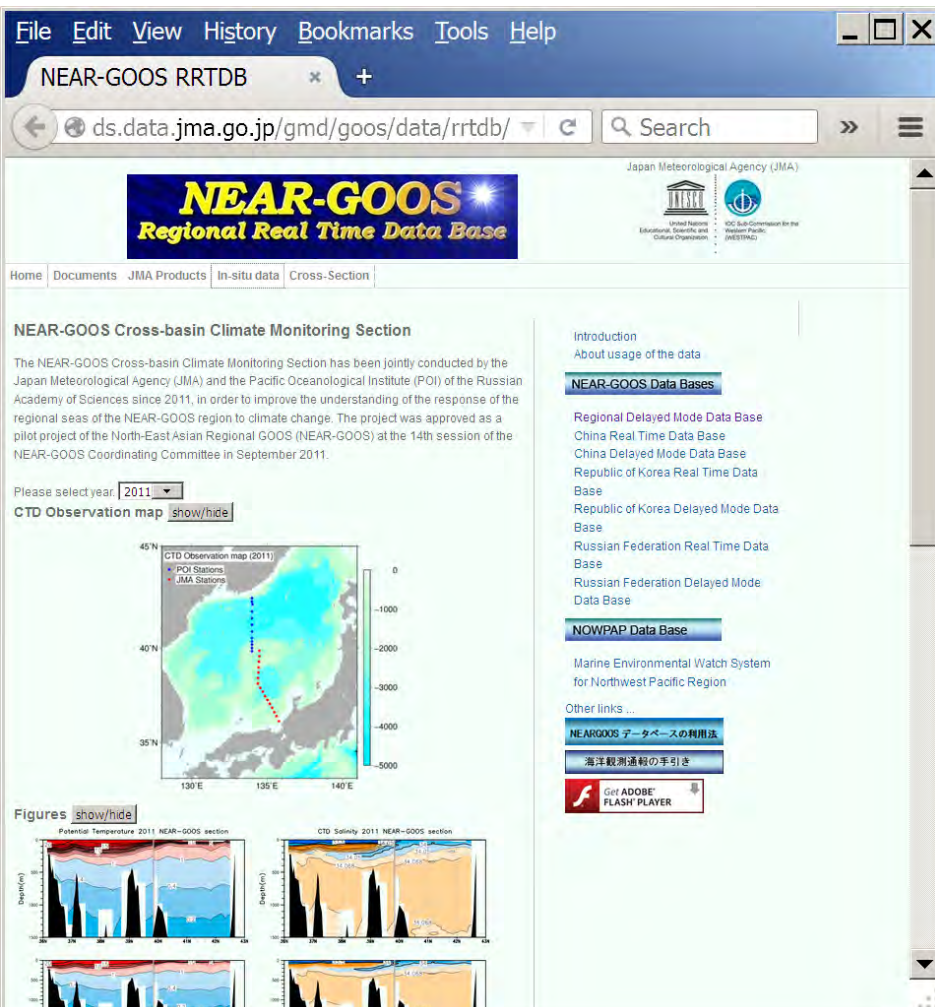


NORTH EAST ASIAN REGIONAL GOOS



NEAR-GOOS Pilot Project: Cross-Basin Climate Monitoring Section

<http://ds.data.jma.go.jp/gmd/goos/data/rrtdb/cross-section/cross-section.html>



Objectives for project:

- JES is semi-enclosed basin with the stable hydrographic structure e.g. cool deep water with the salinity and oxygene anomalies within the intermediate waters;
- The monitoring of these parameters gives a key for understanding of global warming the World Ocean;
- The main idea is to compare the temperature, salinity and oxygene observations made within the close locations which allow to suggest about data quality and compatibility of measurements made independently by the JMA and POI;

Accuracy of SBE sensors

	SBE-35	Temp. SBE-3+	Cond. SBE 4C	O ₂ (SBE-43)	O ₂ (RINKO-III)
Depth measure	to 6800 m	to 7000 m	to 7000 m	to 7000 m	To 7000
Initial accuracy	± 0.001 °C	0.001 °C	0.0003 S/m (0.001 psu)	2% saturation	±2%
Stability	0.001 °C per year	0.0002 °C/month	0.0003 S/m/mon. (0.001 psu/mon.)	0.5% per 1000 hours	±5% (1 month)
Range:	-5 to +35 °C	-5 to 35 °C	0 to 7 S/m	Until 120% surf. sat.	0-200%



- During the study of East Sea deep waters structure within long time it necessary to pay attention on basic characteristics of used sensors for CTD-unit.

SBEDataProcessing : simple case

- Preliminary processing (SBEdataprocessing software.)

Data conversion (binary->ascii)



```
graph TD; A[Data conversion (binary->ascii)] --> B[Align CTD (time lag correction, optional for SBE911)]; B --> C[Cell Thermal Mass correction (correction for warming of sensor cells)]; C --> D[Filtering (get rid of noise, bad data)]; D --> E[Loop edit (exclusion of ship waving, fluctuations)]; E --> F[Bin averaging (averaging data by: pressure/depth/time)];
```

Align CTD (time lag correction, optional for SBE911)

Cell Thermal Mass correction (correction for warming of sensor cells)

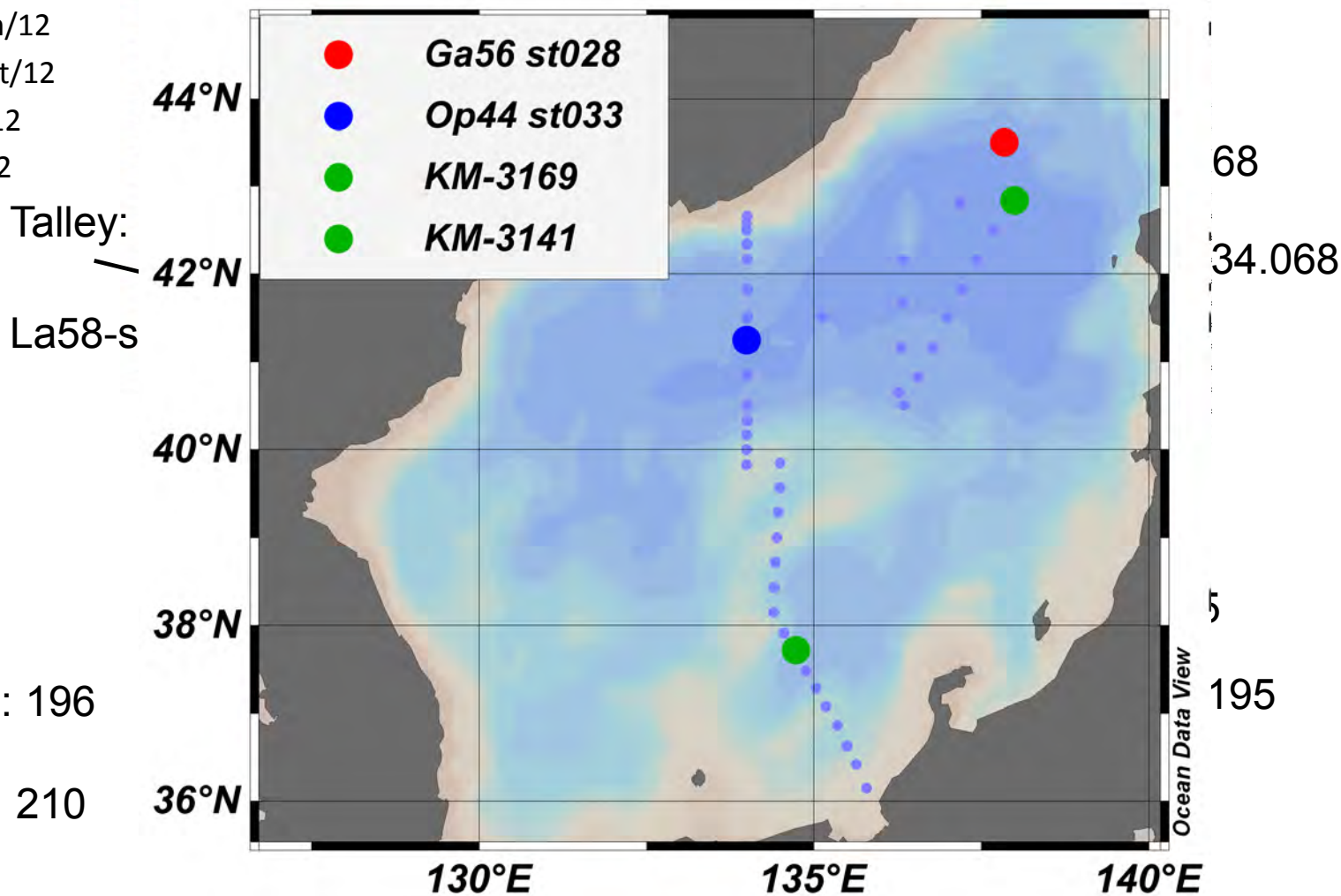
Filtering (get rid of noise, bad data)

Loop edit (exclusion of ship waving, fluctuations)

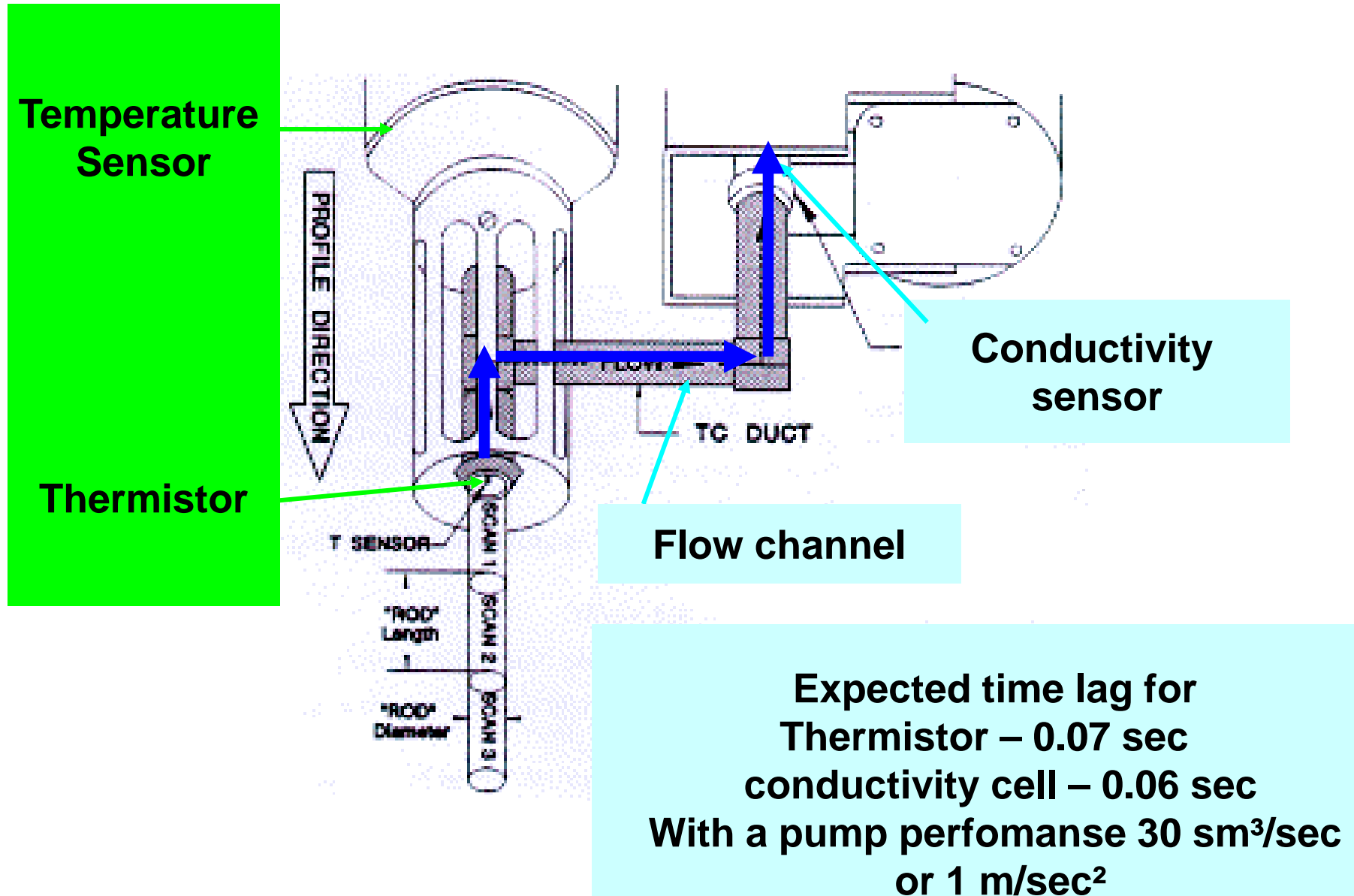
Bin averaging (averaging data by: pressure/depth/time)

Data error assessment by NEAR-GOOS data

- Talley at al. 2004
- Cruise La58 R/V “Akademik M.A. Lavrentyev”, Ga56 R/V “Professor Gagarinsky”, Op44 R/V “Akademik Oparin”
- R/V “Keifu Maru”
- Ga56 St028 – 19/Jun/12
- Op44 St033 – 24/Oct/12
- KM-3141 – 30/Oct/12
- KM-3169 – 4/Nov/12



Temperature and conductivity sensors in SBE



Additional calibration of SBE



GO-SHIP Repeat Hydrography Manual: A Collection of Expert Reports and Guidelines

IOCCP Report No. 14

ICPO Publication Series No. 134

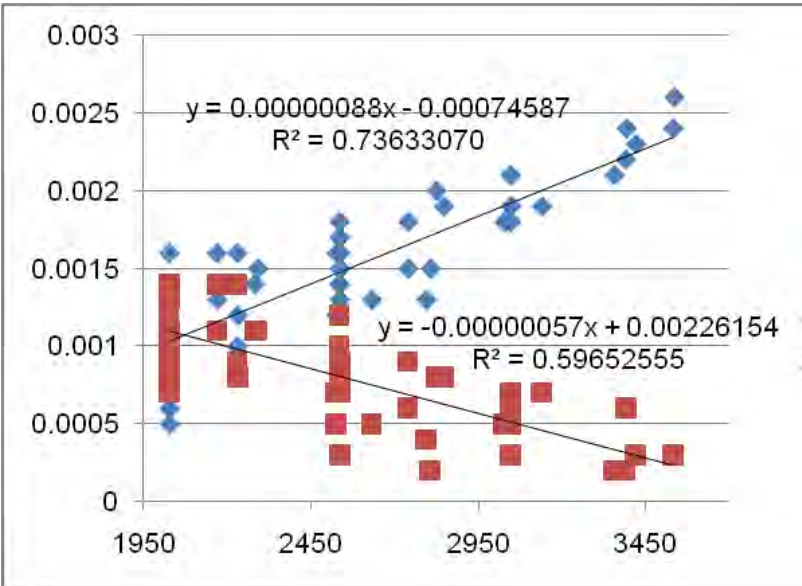
Version 1, 2010



Temperature measurements

La66-2014

[WHP-P9(2010) cruise report. JMA]

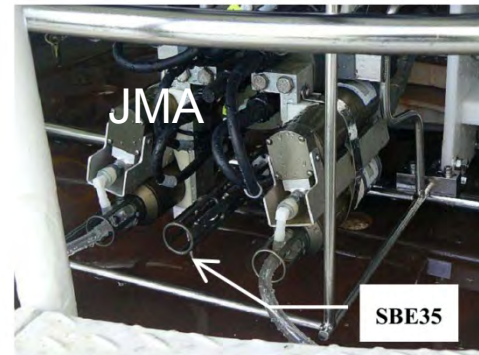


Each SBE-sensor is individual. Its deformation can be corrected at depths more than 2000 m by the calibration using SBE-35 (platinum thermometer).

Usual calibration formula for this case:

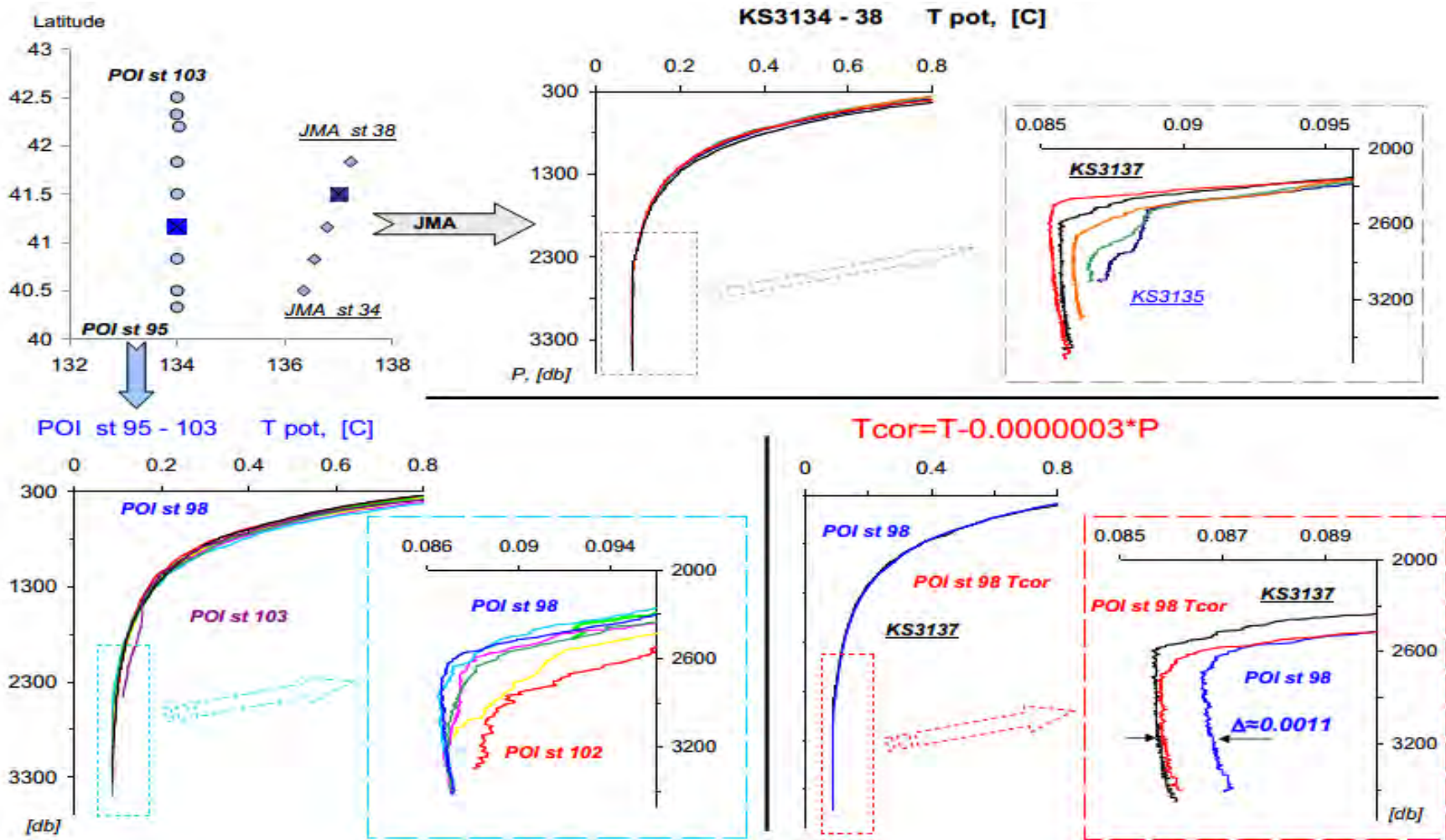
$$T_{cal} = T_{raw} - (C_0 + C_1 \times P)$$

- We used second sensors set (POI) for analysis due to the problem with the 1st one



SBE35

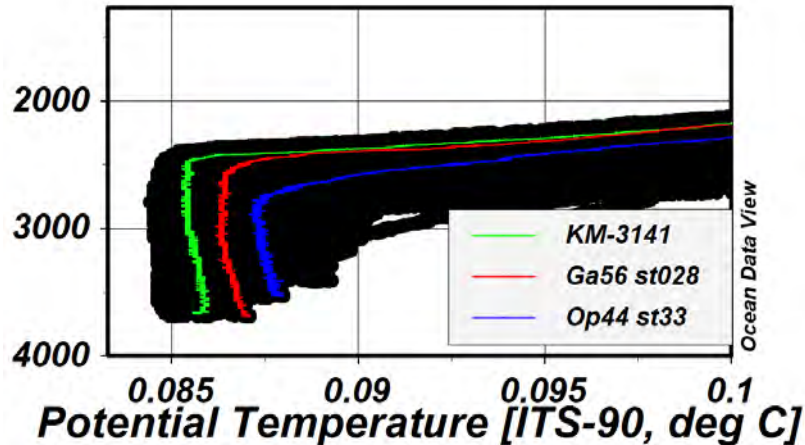
Temperature Correction: without SBE35



Calibration based on PM-Line section, the data from R/V "Keifu Maru" have been Compared with La-58 data (close locations), the SBE35 was not installed

Temperature correction: with SBE35

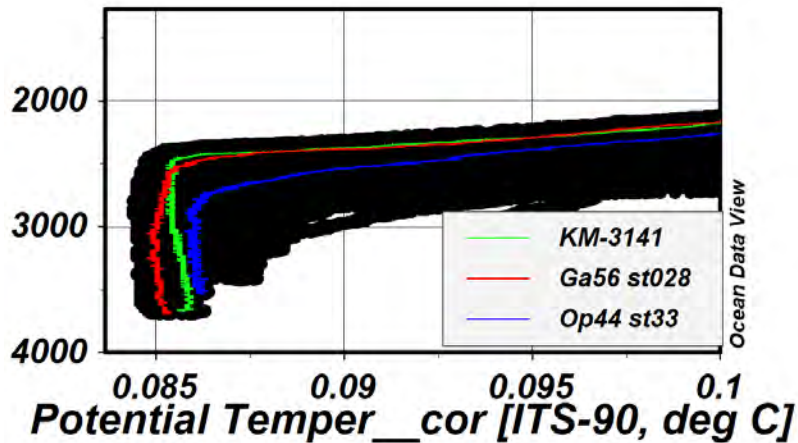
unCalibrated Theta



Ga56 and Op44 data **before** correction

KM3141 – **corrected** data for reference

Calibrated Theta

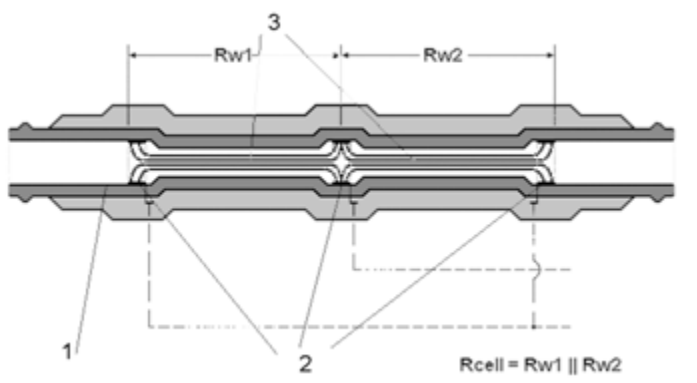


Ga56 and Op44 data **after** correction

KM3141 – **corrected** data for reference

- Correction of temperature on sensitivity to pressure may cause change of T value on ± 0.003 C which may be important during the study of climatic changes

Salinity correction



SBE 4C – conductivity sensor

- to obtain high accuracy it is not enough a standard SBE-processing procedures
- it is necessary to consider pressure effect for SBE conductivity sensor by calibration with data from sampling bottles (together with SBE 35 measurements)

- Correction may be defined using the following formula:

$$C_{cal} = C - \left(\sum_{i=0}^I c_i \times C^i + \sum_{j=1, I=J=2}^J p_j \times P^j \right)$$



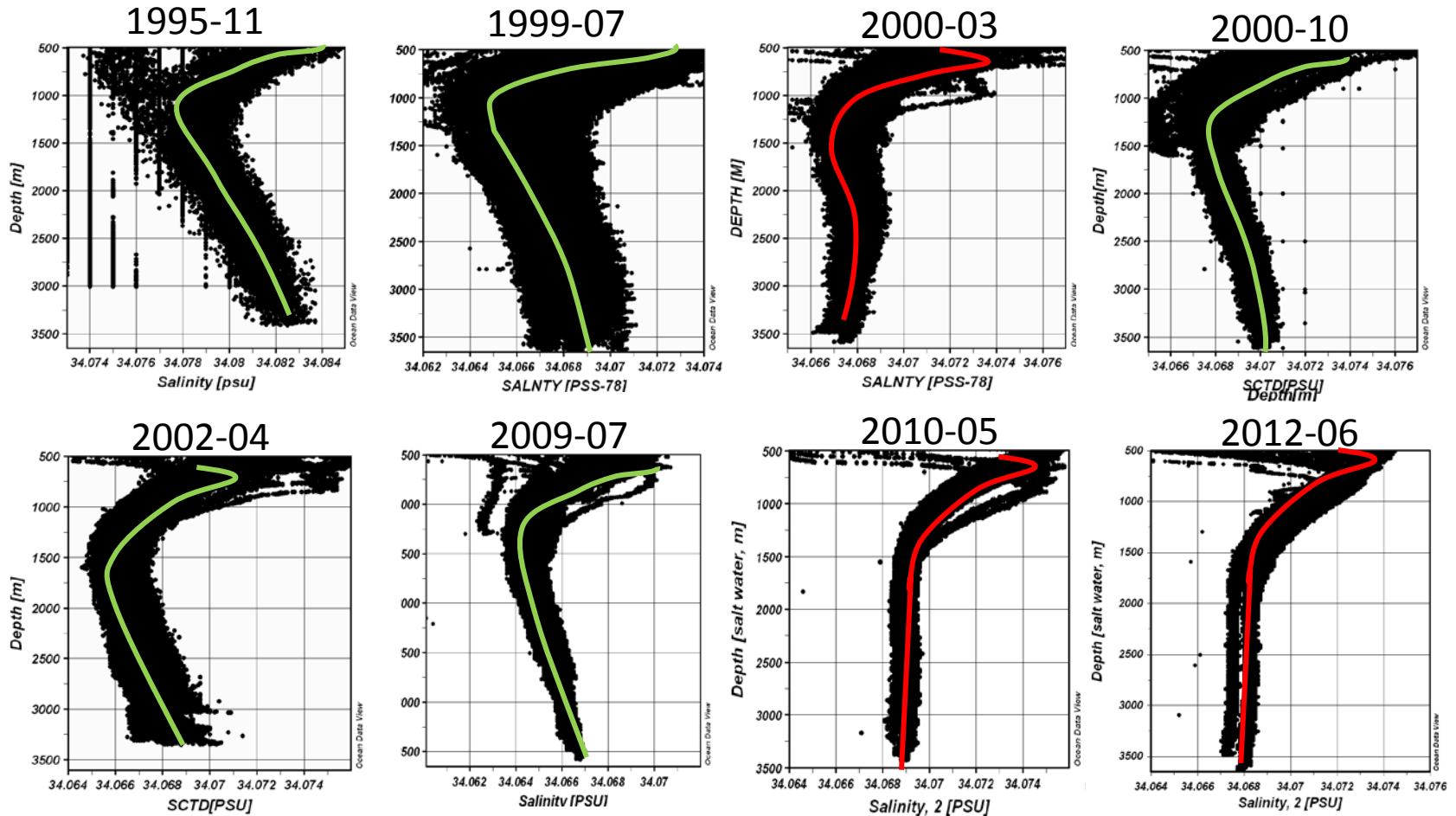
The GO-SHIP Repeat Hydrography Manual: A Collection of Expert Reports and Guidelines

IOCCP Report No. 14, ICPO Publication Series No. 134, Version 1, 2010

**NOTES ON CTD/O₂ DATA ACQUISITION AND PROCESSING USING SEA-BIRD
HARDWARE AND SOFTWARE (AS AVAILABLE)**

K.E. McTaggart, G.C. Johnson, M.C. Johnson, F.M. Delahoyde, and J.H. Swift

Mysterious Deep Salinity Minimum



- Due to polynomial equation of second order sometimes slope and curl is not correctly obtained for intermediate and deep waters of JES

Salinity correction

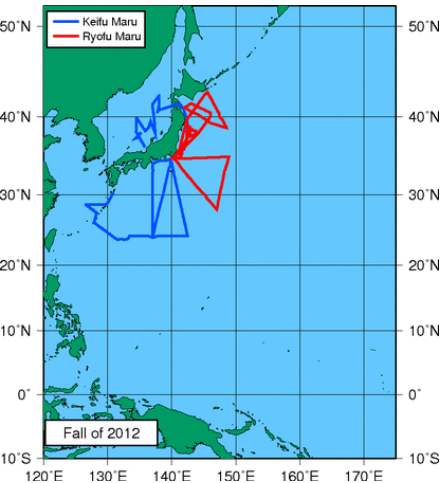
JMA data of cruises of R/V “Keifu Maru” (blue line on map):

http://www.data.kishou.go.jp/kaiyou/db/vessel_obs/data-report/html/ship/ship_e.php

- During the cruise the Laboratory Salinometer was available onboard, which allowed one to make a calibration;



Laboratory Salinometer
Autosal 8400B



Days from July 6, 2010

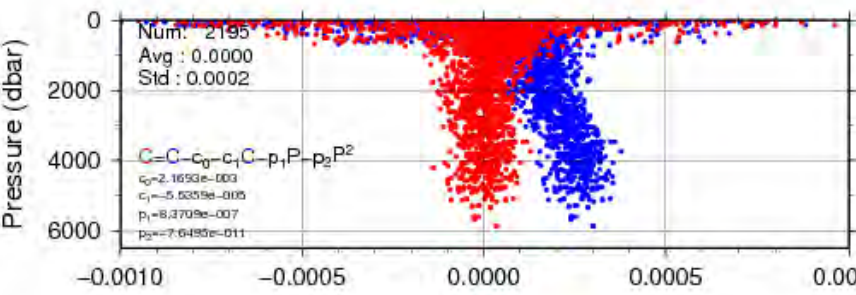
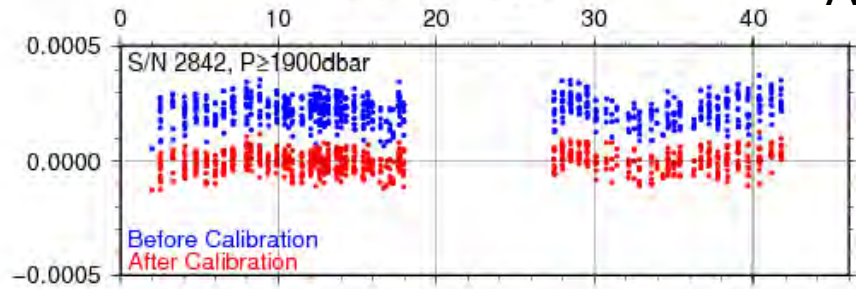


Table C.1.2. Conductivity Calibration Coefficient Summary.

S/N	Num	c_0 (mS/m)	c_1	c_2 (mS/m)	Stations
			p_1 (mS/dbar)	p_2 (mS/m/dbar ²)	
3670	1274	1.5107e-3	-7.4144e-5	0.0000e-0	Stn. 1 – 67
			6.6856e-7	-8.3866e-11	
3670	308	2.2680e-3	-8.0696e-5	0.0000e-0	Stn. 68 – 83, Stn. 105 – 107
			-1.2437e-8	0.5038e-11	
3670	608	1.0048e-3	-7.6991e-5	0.0000e-0	Stn. 84 – 104, Stn. 108 – 124
			3.9031e-7	-4.2466e-11	
2849	2195	2.1693e-3	-5.5359e-5	0.0000e-0	Stn. 1 – 124
			8.3709e-7	7.6495e-11	

Salinity correction

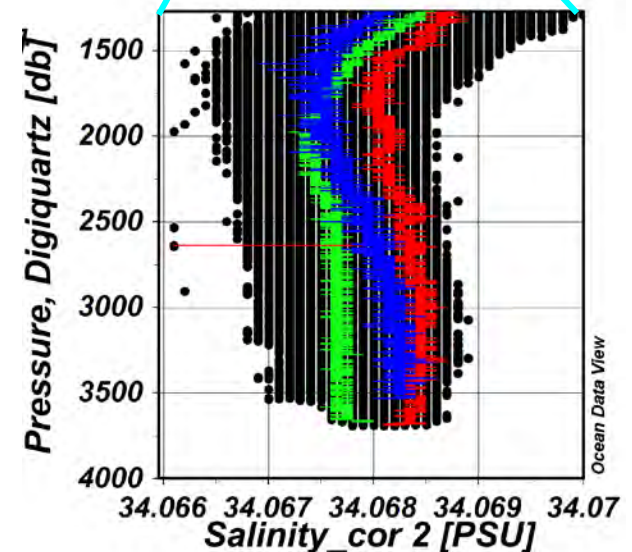
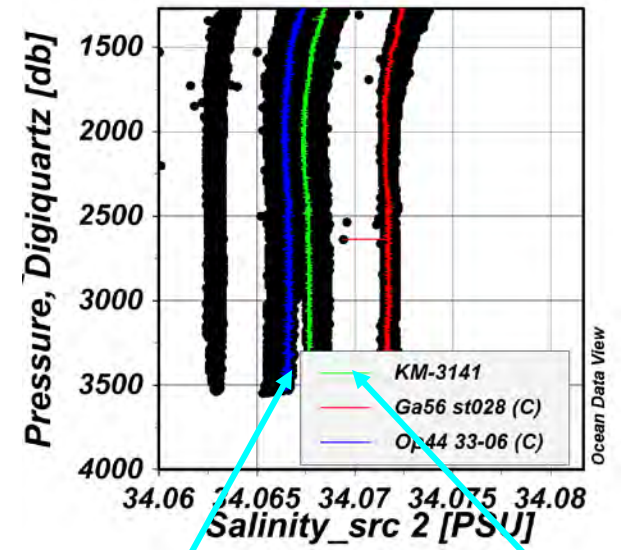
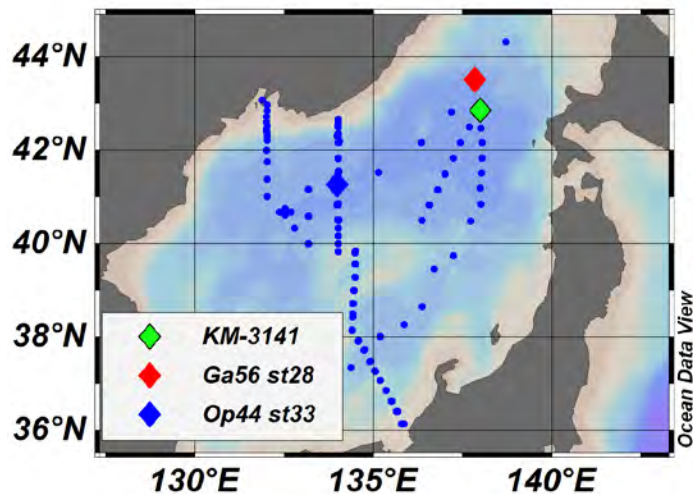
Ga56 and Op44 data **before** correction

KM3141 – corrected data for reference

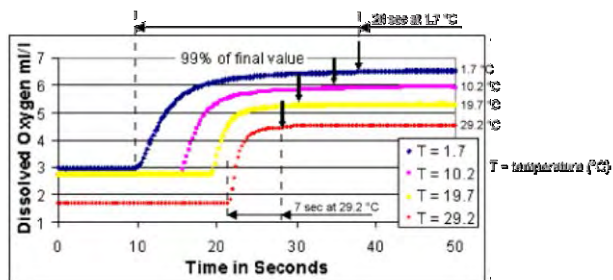
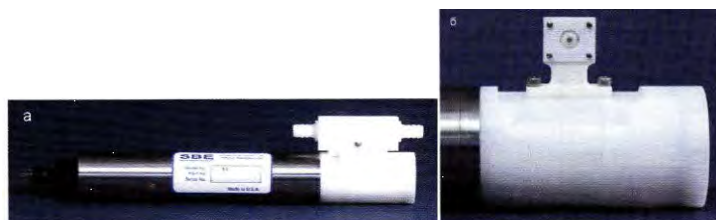
Ga56 and Op44 data **after** correction

KM3141 – corrected data for reference

Temporal drift of conductivity sensor is shown for 127 calendar (36 operated) days



Dissolved Oxygen Measurements



**SBE 43 – O₂ sensor
with polarographic membrane**

$$O_2 = S_{oc} \cdot (V + V_{off} + \tau_{20} \cdot e^{(D_1 \cdot p + D_2 \cdot (T-20))} \cdot dV / dt) \cdot O_{sat} \cdot (1 + A \cdot T + B \cdot T^2 + C \cdot T^3) \cdot e^{[(E \cdot p) / (273.15 + T)]}$$



**Rinko III – O₂ sensor
with optical sensor**

Ref: Gordon, Garcia
Ref: Uchida et al.

$$P_0 = 1.0 + c_4 \times t$$

$$P_c = c_5 + c_6 \times v + c_7 \times T + c_8 \times T \times v$$

$$K_{sv} = c_1 + c_2 \times t + c_3 \times t^2$$

$$coef = (1.0 + c_9 \times P / 1000)^{1/3}$$

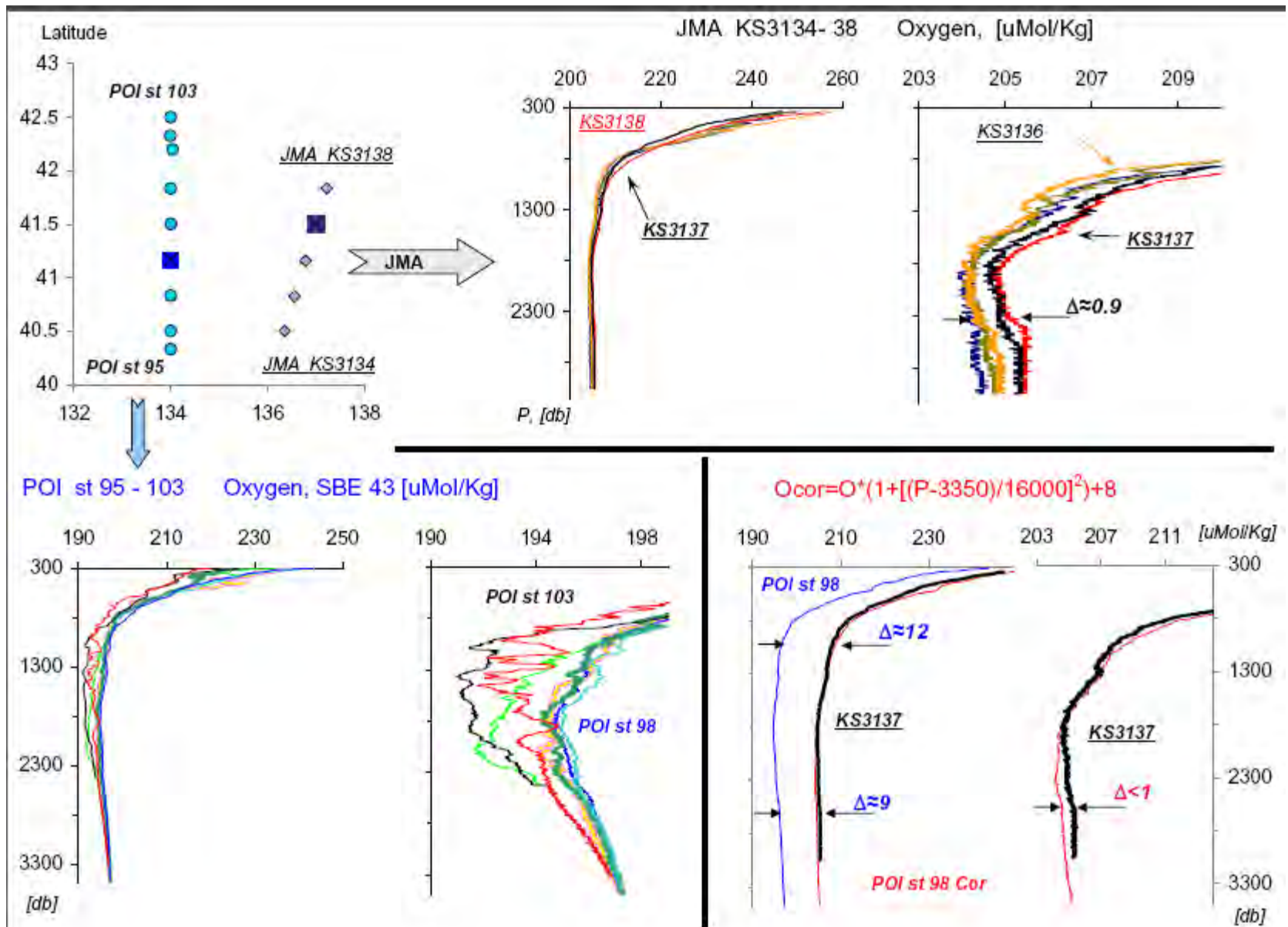
$$[O_2] = \left\{ (P_0 / P_c - 1.0) / K_{sv} \times coef \right\}$$

Owens, W. B., and R. C. Millard Jr., 1985: A new algorithm for CTD oxygen calibration. J. Physical Oceanography., 15, 621-631.

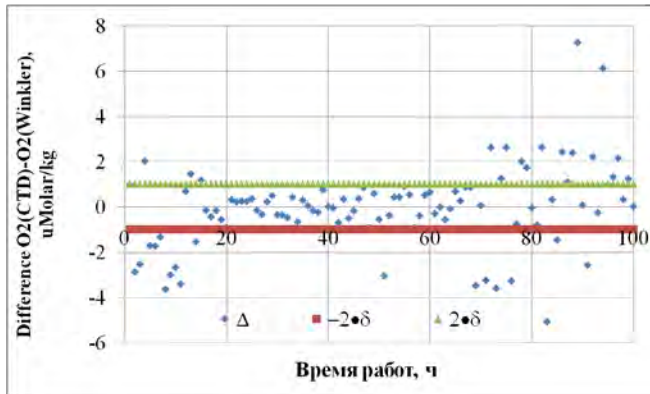
Garcia and Gordon (1992) "Oxygen solubility in seawater: Better fitting equations", Limnology & Oceanography, vol 37(6), p1307-1312.

Uchida, H., T. Kawano, I. Kaneko, and M. Fukasawa (2008): In-situ calibration of optode-based oxygen sensors. J. Atmos. Oceanic Technol., 25, 2271-2281.

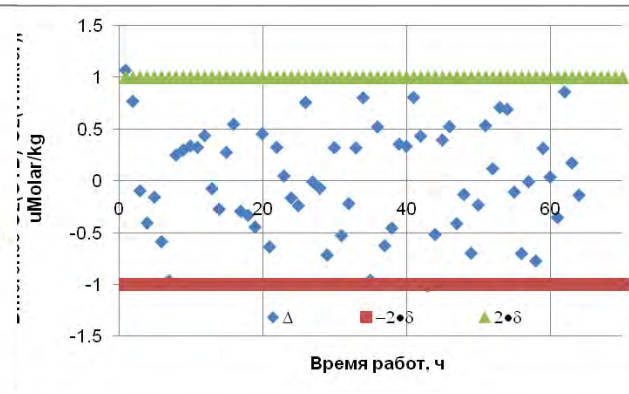
DO correction: no samples



Optical (Rinko)/ Membrane (SBE43) correction

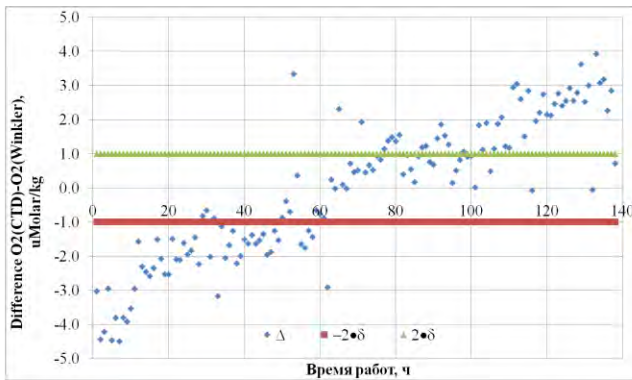


(a)

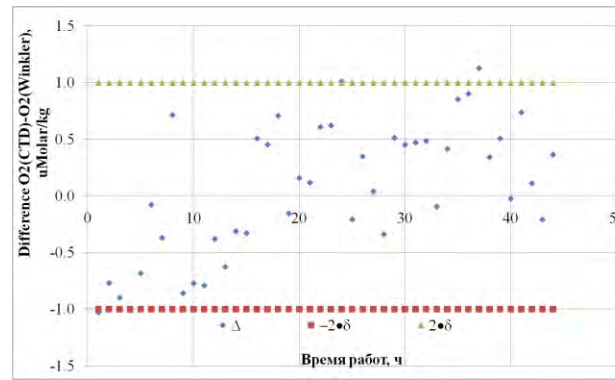


(b)

La 64 – steps of choice with 2sigma criteria for RINKO III



(a)

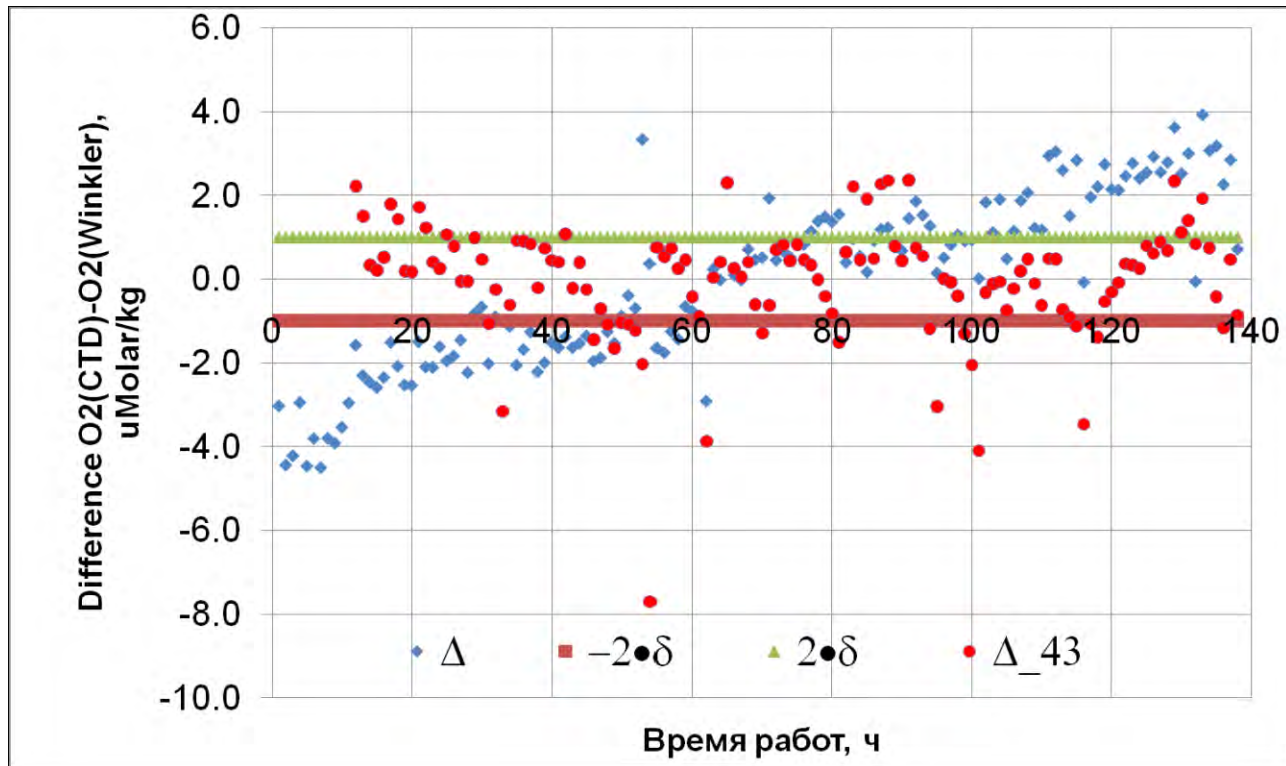


(b)

La 66 – steps of choice with 2sigma criteria for RINKO III

The analysis showed different behavior of sensor during two different cruises

Optical (Rinko)/ Membrane (SBE43) correction

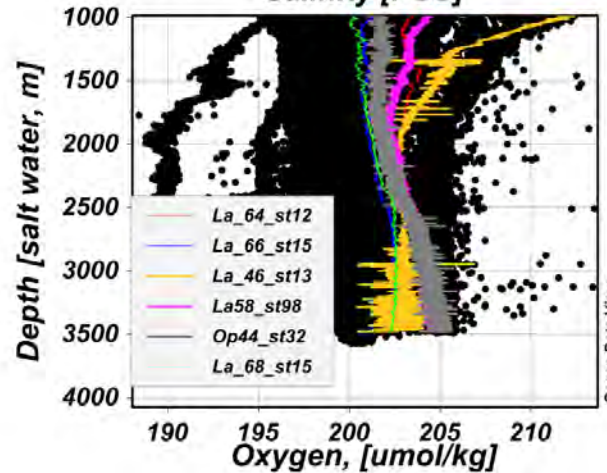
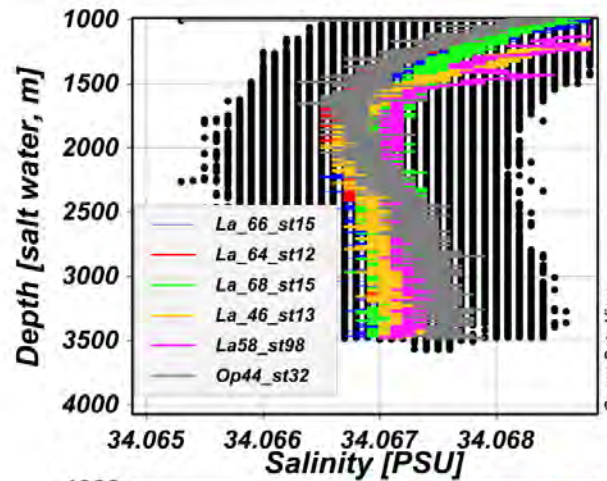
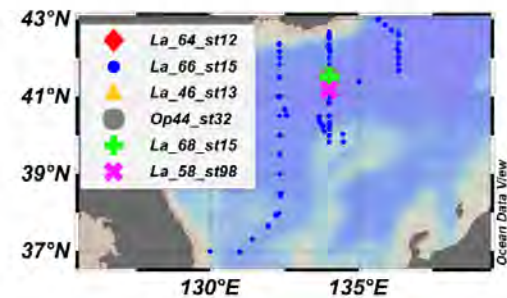
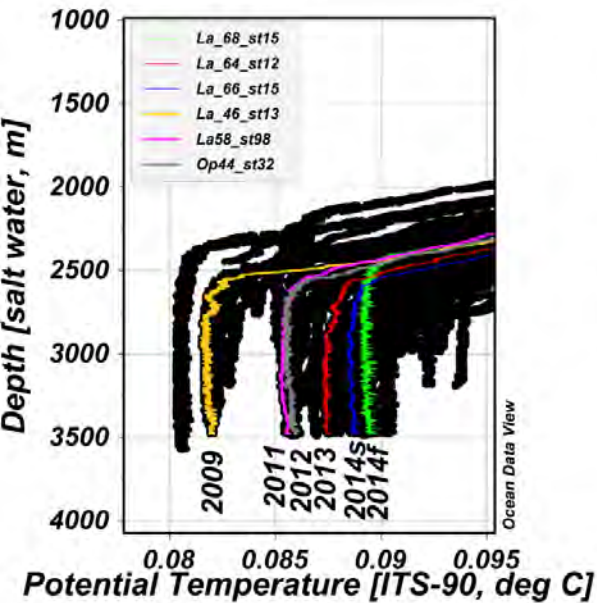


Comparatively with the SBE43 RinkoIII has a temporal drift which is not similar for different cruises

This cause us to use only 30% of obtained data for calibration in the La66 cruise

According with this the RinkoIII sensors needs to be inspected and controlled during the further cruises

Calibrated data comparison (2009-2014)



Finally were defined:

- Temperature corrected in the same manner for the last 5 years essentially increases;
- The temperature growth is not regular from year to year;
- The salinity minimum is stable within the frames of instrument sensitivity;
- The oxygen in the deep layer has some variations and now is lower than 3 years before, but rather oscillate than increases;

Conclusions

1. To identify interannual and spatial variations of deep and bottom water parameters in the JES an accuracy of ± 0.001 is required for temperature and salinity.
2. T, S and dissolved oxygen intercalibration and correction of data is important.
3. Calibration of SBE43 and RINKO-III DO-sensors is available by samples analysis (Winkler chemical method) and by comparison of POI and JMA data.
4. Optical sensor (RINKO-III) sensor has some peculiarities which need to take into account during the oxygen calibration.
5. Continuation of NEAR-GOOS Cross-Basin Section will provide reliable data on deep and bottom water response of the sea to climate changes.

謝謝!

Thank you for your attention!

СПАСИБО!